

Physics Section 3.3: Keeping Things Moving

Magnetic Fields

- That a magnetic field is a region where magnetic materials and current-carrying wires experience a force acting on them.
- That when a current flows through a wire, a magnetic field made up of concentric circular field lines is formed in a plane perpendicular to the wire with the wire at the centre.
- That an electromagnet is a magnet that can be turned on and off using a current.
- That electromagnets are used in things like scrap metal cranes and relay switches.

The Motor Effect

- That when a current-carrying wire in a magnetic field experiences a force it's called the motor effect.
- That the force caused by the motor effect can be increased by increasing the current in the wire or increasing the magnetic field strength.
- That if a current-carrying wire is parallel to a magnetic field, it will experience zero force due to the motor effect.
- That the two ways of reversing the direction of the force caused by the motor effect are reversing the current and reversing the magnetic field.
- How to use Fleming's left-hand rule to find the direction of the force caused by the motor effect.

Using the Motor Effect

- That the motor effect can be used to create motion, e.g. in a simple electric motor.
- That a simple electric motor can be made using a current-carrying loop of wire, a magnetic field and a split-ring commutator. The motor effect causes a force that causes the loop of wire to turn, and the split-ring commutator ensures the force is always acting in a direction that keeps the loop turning.

Electromagnetic Induction

- That a potential difference is induced across the ends of a wire (or other conductor) when it moves within a magnetic field or a magnet is moved inside it.
- That an a.c. current can be generated by changing the direction of a magnet moving relative to a conductor, or a conductor moving relative to a magnetic field.
- How to apply knowledge of electromagnetic induction to different electrical appliances that make use of it.

Transformers

- That a transformer consists of a primary coil and a secondary coil, wrapped around an iron core.
- How an alternating current in the primary coil creates a changing magnetic field in the iron core and secondary coil of a transformer. Know that as a result, an alternating p.d. is induced by electromagnetic induction across the ends of the secondary coil.
- That in a step-up transformer the number of turns on the secondary coil and the potential difference across it are greater.
- That in a step-down transformer the number of turns on the primary coil and the potential difference across it are greater.
- How to use the transformer equation:
$$\frac{V_p}{V_s} = \frac{n_p}{n_s}$$
- where V_p and n_p are the potential difference across and number of turns on the primary coil, and V_s and n_s are the potential difference across and number of turns on the secondary coil.
- That if a transformer is assumed to be 100% efficient, then its power input is equal to its power output and so:

- $V_p \times I_p = V_s \times I_s$
 - where V_p and I_p are the potential difference across and current in the primary coil, and V_s and I_s are the potential difference across and current in the secondary coil.
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Switch Mode Transformers

- That switch-mode transformers operate at frequencies that are much higher than traditional transformers — often in the range of 50–200 kHz.
- That switch mode transformers are small and light, and use very little power if they have no load.
- That switch mode transformers are ideal in situations where they're likely to be plugged in for a long time or carried around, such as the chargers for phones or laptops.